# Usermanual VERMPACK

Collection of landsurveying software for HP 41CX emulators



Copyright: Johannes Grösbrink (Code and manual), Angel Martin (VERMPACK\_2A.MOD)

VERMPACK Version 2.0 released May 2014

## Documentrevisions

Datum	Versions- nummer	Änderungen			
12.04.2014	V1.0	first published manual			
28.04.2014	V1.1	Additions to the point management			
08.05.2014	V2.0	Transformed to a HP41-Module by Angel Martin			
		Translated manual in english			

## Whats new in V2.0?

- 1. Version 2.0 comes as a module and so it is separated from the Hepax storage. Thanks so much for that, Angel Martin!
- 2. New program **RENPKT** : allows to rename pointnumbers
- 3. Program **LSTPKT** works better: It only shows used pointnumbers and at last gives the number of storable points left.
- Input of unknown pointnumbers in the programs now does not any more deliver error messsages, but allows the input of correct pointnumbers or to break the program.

## Index

1		INTF	RODUCTION	4
	1.	.1	About VERMPACK	4
	1.	. 2	Overview	5
	1.	. 3	Principles	6
2		DESC	CRIPTIONS	7
	2.	.1	Pointmanagement	7
		2.1.	.1 Input Points	7
		2.1.	.2 Query Points	8
		2.1.	.3 List Points	8
		2.1.	.4 Rename Points	8
		2.1.	5 Delete Points	9
	2.	. 2	Management of Coordinate Systems	9
		2.2.	.1 Local coordinate System	9
		2.2.	.2 Gauss-Krueger coordinate System	9
		2.2.	.3 ETRS89/UTM coordinate System	10
		2.2.	4 Distance Reduction (Nature Distance to projected Distance)	10
		2.2.	5 Distance Reduction (projected distance to Nature Distance)	10
	2.	. 3	TRIANGLE CALCULATIONS	12
		2.3.	1 Altitude and Linesegments	12
	2.	. 4	Circle- and Arc Calculations	13
		2.4.	.1 Staking out Circlepoints from a Tangent	13
		2.4.	.2 Staking out Circlepoints from a Chord	14
		2.4.	.3 Center of a Circle with 3 Points	15
	2.	. 5	INTERSECTIONS	16
		2.5.	.1 Intersection of two Lines	16
		2.5.	.2 Perpendicular on a Line	17
		2.5.	.3 Intersections of a Circle and a Line	18
		2.5.	.4 Intersections of two Circles	19
	2.	. 6	TRANSFORMATIONS	20
		2.6.	.1 Orthogonal point calculation	20
		2.6.	.2 Calculation of Abszissa and Ordinate	22
		2.6.	.3 Helmert Transformation	24
	2.	.7	Polar Methods	26
		2.7.	.1 Direction Angle and Distance	26
		2.7.	.2 Resection - Calculate the Station	27
		2.7.	.3 Resection - Stakeout Points	28
	_	2.7.	.4 Resection - Measure new Points	29
	2.	. 8	AREACALCULATION	30
		2.8.	.1 Area of a Polygon	30
		2.8.	.2 Heron's Formula	31
3		APPE	ENDIX	32
	3.	.1	LISTINGS	32

## 1 Introduction

#### 1.1 About VERMPACK

The HP41CX was one of the best programmable calculators of its time and has recently celebrated its 30th anniversary.

Even today, many of these devices with the practical UPN notation are active in circulation and used by engineers and technicians. There are lots of emulators of the HP41 today, for example *Olivier De Smet* has revived this computer with his app go41CX fully functional to life again. Unlike many other PC emulators this app makes it to a real mobile device again. Also V41, developed by *Warren Furlow* does wonderful work on Windows devices.

The surveying program package "VERMPACK" which is documented in this manual contains many programs that I have written during my studies for this device. Fortunately I found the source code after 25 years. VERMPACK is running on both emulators mentioned above.

VERMPACK comes as a module, especially compiled by *Angel Martin*. I thank him very much for that and thanks also for all the interesting explanations about the HP41 he offered to me.

Of course, I have added some new programs, for example a point management, which is very useful in combination with the magic HEPAX memory, and the reduction of distances for the ETRS89/UTM coordinate system and for the Gauss/Krueger coordinate system.

The programs for resection originate as far as I remember from our Professor of Surveying Dr. Hanns Severin Haase, but were adapted in some details because of the built- in VERMPACK point management and distance reduction.

The whole package is more interesting for HP41CX enthusiasts as for users who need to earn money in today's surveying.

Nevertheless the fairly simple knitted system is able to quickly perform calculations in particular, if no other means are available.

Also the program is interesting for trainees, who thus on their smartphone have a convenient and meaningful education accompanying calculation software for a very reasonable price.

### 1.2 Overview

All the programs of VERMPACK build a matched system, connected by the point management. Only a few programs do not require the point management. The system uses the hepax module and is delivered in a module. Please load 3 empty hepax files in slot 1-3 and the VERMPACK.mod in slot 4. A special overlay with graphical icons for the user mode supports the user in the orientation on the surface. (See the illustration on the title page). All programs are called with mand the appropriate FUNCTIONKEY.

Approximately 650 points can be stored in the hepax-system. All points are calculated in 2D and stored since the system was originally designed for cadastral tasks.

The program code is freely available and can easily be supplemented or modified as necessary.

The author is not liable for damage to software or hardware or economic losses arising from the use of the programs, unless these are due to gross negligence or intent on the part of the author, his agents, or his legal representatives.

reserved Re	gisters						
REG 49	Point-Management						
REG 48	Point-Management						
REG 47	Reduction of distances and areas						
REG 46	Reduction of distances and areas						
REG 45	Reduction of distances and areas						
REG 44	Reduction of distances and areas						
REG 43	Point-Management						
REG 42	Point-Management						
REG 41	Point-Management						
REG 40	Point-Management						
REG 00	Point-Management						
reserved Flags							
FLAG 01	Local Coordinate System is active						
FLAG 02	2 Gauss-Krueger Coordinate System is ative						
FLAG 03	ETRS89/UTM Coordinate System is active						

Some registers and flags are reserved for certain values , and therefore should not be overwritten during the calculations:

Please always make sure that the correct coordinate system is set (indicated by the flags). The coordinate system controls the reduction of distances and areas in the following Programs:

 KOKLEIN
 SPRJNAT
 SGK
 FRSTAT
 FRMESS
 RIWI
 KREISM
 AREA

 KOELEM
 SNATPRJ
 SKK
 FRABST

All keyboard tracks and all displayed distances and areas are measured distances and areas in the field, independent from the active coordinate system. So the user does not have to think about reduction.

## 1.3 Principles

The VERMPACK represents an integrative program system of various subprograms which work together with the Hepax system and Main Memory as follows:



To install VERMPACK, in go41cx switch of the calculator, load three empty HEPAX Memory Files in Slot 1-3 and the VERMPACK.MOD in slot 4 and switch on the hepax-system.

In V41 switch of the calculator, load the Hepax.mod in slot 1, the Hepaxmem.mod in slot 2 and the VERMPACK.MOD in slot 3. The V41 switches on by itself then.

Because the HEPAX Memory Files are just used for storing Coordinates, you can projectwise create HEPAX Memory Files and load them, if necessary.

## 2 Descriptions

In this Chapter the individual programs which are delivered with  $\ensuremath{\mathsf{VERMPACK}}$  are described.

#### 2.1 Pointmanagement

VERMPACK has a small point management, applicable to all functions in which coordinates are determined.

Each point is saved in the HEPAX memory as a file. The file name is corresponding to the pointnumber. In VERMPACK about 650 points can be stored in one project (i.e. in one Triple of HEPAX Memory files)

Note that the pointnumbers must be unique, must contain only numbers and have a length of a maximum of 5 digits! After the calculation of a point, the program asks for the corresponding pointnumber. When entering the pointnumber "0", the point is not saved.

In the created HEPAX file for the point, the coordinates in the order Easting, Northing are stored. In VERMPACK no point codes are provided, but only coordinates are stored. There are no heights managed.

If in a calculation program under a specified pointnumber no point is found, a corresponding message appears and the pointnumber can be corrected.

The following functions for point management are available:

#### 2.1.1 Input Points

With the SET Command, new points can be entered.

Eingabe im User Modus	Display	
E+ oder XEQ SETPKT	🗌 PKT EINGR <b>i</b> e	
	PNR7	<b>~</b>
1234567 R/S	RECHIST	1 1
58693.25 R/S	HOEH7	1
100.123 R/S	۵ĸ	

If a point with the entered pointnumber exists, it can be decided whether to enter another pointnumber or to overwrite the coordinates of the corresponding point:

1=overwrite the coordinates
0=suggest a new pointnumber

This function is running, until another function is called.

#### 2.1.2 Query Points

The GET Command is used to query Point information. The Poinnumber is entered, to get the coordinates in the display.

Input in User	Mode	Display	
1/x or	XEQ GETPKT	РКТ ЯЈFRAGE	
		PNR7	<b>←</b>
1234566	R/S	RECHISWERT	
	R/S	HOEHWERT	

If there is no Point to the given Pointnumber, there is the error message "PUNKT FEHLT" and the System asks again for a Pointnumber.

This function is running, until another function is called.

#### 2.1.3 List Points

The LIST Command lists all Pointfiles stored in the HEPAX System. All pointfiles are listet by their name. At last the number of points which can be stored is shown.

Input in User Mode	Display
SQRT or XEQ LISTPKT	PKT LISTE
	PUNKINUMMER I
Pointnumbers	
number of storable points	FREI: 650

#### 2.1.4 Rename Points

The REN Command is used to rename Pointnumbers. Therefore the old Pointnumber and the new Pointnumber must be entered.

Input in User Mode	Display	
LOG or XEQ RENPKT	PNR RENIERN	
	ALTE NR7	
1000	NEUE NR7	
2 103	OK/GESCHEITERT	

If there is no Pint with the old Pointnumber, or if a point already exists with the new Pointnumber, the program shows the error Message "**DESCHEITERT**", otherwise the message will be "**DK**"



#### 2.1.5 Delete Points

With the DEL Command Points can be deleted.

Input in Use	r Mode		Display		
LN or	XEQ	DELPKT	PKT LOESCHEN		
			PNR7	-	
1234262	R/S			_	

This function is running, until another function is called.

## 2.2 Management of Coordinate Systems

VERMPACK works with three different Coordinate systems, the German Gauß-Krüger, ETRS89/UTM and local systems.

It is absolutely recommended to set the correct System, because only so the correct projections for distances and areas can be calculated. The Configuration of the coordinate system works with the program SYSUM and SYSLOK.

The active system can be controlled with the Flags 1-3, which are especially reserved for this job in VERMPACK.

Flag 1 : local System is active

Flag 2 : Gauß-Krueger System is active

Flag 3 : ETRS89/UTM System is active

The reductions are calculated with the middle coordinate of the area and not with coordinates of the used points themselves. So Gauß-Krueger-coordinates and ETRS89/UTM-coordinates can be entered without leading digits.

#### 2.2.1 Local coordinate System

The program sets the active coordinate system to a local system with the scale 1.0000. No projection is calculated for this system. It is used for engineering systems on construction sites.

Input in User Mode	Display
SIN or XEQ SYSLOK	SET LOKALSYS
	SYS: LOKAL

Flag 1 is active!

The coordinate system remains, until you change it.

#### 2.2.2 Gauss-Krueger coordinate System

The program asks for the distance to the central meridian of the Gauss-Krueger system [km], the earth radius [km] and the mean ellipsoidic Height of the survey area [m]. If the ellipsoidic Height is not known, the NHN-Height can be used.





Input in User	Mode	Display
R or	XEQ SYSGK	SET GK-SYS
		RJST.MERZKM17
(62	R/S	RAJIUS7KW75
638 (	R/S	H ELLZM17
145,025	R/S	5 Y 5: 6 K

Flag 2 ist active!

The coordinate system remains, until you change it.

#### 2.2.3 ETRS89/UTM coordinate System

The program asks for the distance to the central meridian of the ETRS89/UTM Zone [km], the earth radius [km] and the mean ellipsoidic Height of the GRS80 Ellipsoid of the survey area [m]. In Germany as a good value NHN + 45,00m can be used.

ean	elliğ	)so:	Lai	LC .	неј	gnt	01	t the	€
Gei	rmany	as	а	go	od	valı	Je	NHN	+

Input in User	Mode	Display
X<>y or	XEQ SYSUTM	SET SYS-UTM
		AJST.MER/KM72
(62	R/S	ERJRAJIUSZKMYŻ
638 (	R/S	HELLZM17
(45,025	R/S	SYS: UTM

Flag 3 ist active!

The coordinate system remains, until you change it.

#### 2.2.4 Distance Reduction (Nature Distance to projected Distance)

This calculates the projected length  $S_\kappa$  of a natural distance  $S_N$  in the active coordinate system.

SNATUR = measured distance
SK = projected distance (Mapdistance)

Input in User	Mode	Display	
TAN or	XEQ SNA	NRTURLKARTE	
		5 NATUR7	<b>~</b>
245, <b>0</b> 45	R/S	5K = 245,089	

In a local system both distances have the same length!

#### 2.2.5 Distance Reduction (projected distance to Nature Distance)

This program calculates the natural distance  $S_{N}$  from a given Mapdistance  $S_{\kappa}$  in the active coordinate system.





SKARTE = projected distance (Mapdistance)
SN = measured distance (natural distance)

Input in User	Mode	Display	
Cos or	XEQ SPRJNAT	KARTEZNATUR	
		5 KARTE7	
245,089	R/S	5N=245,045	

In a local system both distances have the same length!

#### Formulas to Chapter 2:

local systems:

## $S_{Karte} = S_{Natur}$

Gauss-Krueger and ETRS89/UTM:

$$S_{Karte} = S_{Natur} * \left[ \left( 1 - \frac{H_{ell}}{R} \right) * \left( 1 + \frac{(E_m - 500)^2}{2R^2} \right) * M \right]$$

$$S_{Karte} = S_{Natur} / \left[ \left( 1 - \frac{H_{ell}}{R} \right) * \left( 1 + \frac{(E_m - 500)^2}{2R^2} \right) * M \right]$$

Sgem = measured distance Sproj = projected mapdistance Hell = ellipsoidic Height in [m] R = earth radius in [km] Em = Easting of the central meridian in [km] M = 1.0000 at Gauss-Krueger M = 0.9996 at ETRS89/UTM

## 2.3 Triangle Calculations

#### 2.3.1 Altitude and Linesegments

The program calculates from the three sides  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$  of a triangle the height  $\mathbf{h}$  and the segments  $\mathbf{p}$  and  $\mathbf{q}$ .



Input in User	Mode	Display	
0 or	XEQ HHFP	IREIECK	
		SEITE @7	4
28 (	R/S	SEITE 67	
4.73	R/S	SEITE c7	
) P.E	R/S	P=3411	
	R/S	0 = 0.499	
	R/S	H=4.704	

If the sides of the triangle must be calculated from coordinates, use the program "Direction Angle and Distance" to calculate the natural distances. Remember to use the correct coordinate system!



## 2.4 Circle- and Arc Calculations

#### 2.4.1 Staking out Circlepoints from a Tangent

The program calculates abszissas  $a_i$  and ordinates  $o_i$  from a tangent onto an arc given by the radius R, the starting abszissa  $\bm{x}$  und equal abszissa deltas  $d\bm{x}$ .



Input in User	Mode	Display	
3 or	XEQ ABKBT	ABST.TANG.	
		RAJIU57	
50.00	R/S	X 7	<b>~</b>
5.00	R/S	ЧХ7	
Ø	R/S	A = 2.0 0	
	R/S	0 = 0.25 (	

or

Input in User	Mode	Display	
3 or	XEQ ABKBT	ABST.TANG.	
	R/S	RAJIU57	
50.00	R/S	X 7	
5.00	R/S	ЧХ <sup>7</sup>	
3.0 O	R/S	A = 5.00	
	R/S	0 = 0.25 (	
	R/S	R = 8.0 0 0	
	R/S	0=0.544	

In the first method  ${\bf x}$  is entered,  $d{\bf x}$  is zero. The corresponding ordinate  ${\bf o}$  will be calculated for  ${\bf x}.$ 

In the second method  $d{\bm X}$  is different from zero and the program calculates the first ordinate  ${\bm o}$  and then further ordinates  ${\bm o}$  at abszissas  ${\bm a}$  at multiple distances of  $d{\bm X}.$ 

If the abszissa becomes longer than the radius, the program shows "ZU WEIT".

#### 2.4.2 Staking out Circlepoints from a Chord

The program calculates ordinates  $o_i$  at given abszissas  $a_i$  on a chord of a circle with given radius R, starting abszissa x und delta abszissas dx.





Input in User	Mode	Display	
2_ or	XEQ ABKBS	A 15 I.SEHNE	
		RAJIU57	
50.00	R/S	L SEHNE7	
(5.00	R/S	X 7	
5.00	R/S	ЧХ7	
Ø	R/S	R <u>-</u> 5.0 0	
	R/S	0 = 0.5 0 3	

or

Input in User	Mode	Display
2 or	XEQ ABKBS	ANST.SEHNE
		RAJIU57
50.00	R/S	L SEHNE7
(5.00	R/S	X 7
5.00	R/S	4×7
3.0 Ø	R/S	A = 5.00
	R/S	0 = 0.5 0 B
	R/S	R = 8.000
	R/S	0:0.563

In the first method  ${\bf x}$  is entered,  $d{\bf x}$  is zero. The corresponding ordinate  ${\bf o}$  will be calculated for  ${\bf x}.$ 

In the second method  $d\mathbf{X}$  is different from zero and the program calculates the first ordinate  $\mathbf{o}$  and then further ordinates  $\mathbf{o}$  at abszissas  $\mathbf{a}$  at multiple distances of  $d\mathbf{X}.$ 

#### 2.4.3 Center of a Circle with 3 Points

The program calculates the center M and the radius R of a circle defined by three points  $P1,\ P2$  and P3, which are placed on the edge of the circle.





Input in User	Mode	Display	
6 or	XEQ KREIS	KREISMITTELPKT	
		ም (?	<b> </b>
101	R/S	P27	
(02	R/S	P37	
(Ø 3	R/S	R = 52,235	
	R/S	YM=2586200,125	
	R/S	XM=57 (5520, 123	
	R/S	PNR7	
PNR or 0	R/S		

After the calculation the center will be stored, if the pointnumber differs from zero.

The radius is expected as natural distance, the projection is applied automatically. Therefore use the programs SYSGK, SYSUTM or SYSLOK as explained in 2.2.

## 2.5 Intersections

#### 2.5.1 Intersection of two Lines

The program calculates the intersection  ${\bf S}$  oft wo lines, which are defined by the four points **P1-P2** und **P3-P4**.





Input in User	Mode	Display	
<- or	XEQ SGG	SEHNITT 6/6	
		P (7	
101	R/S	P27	-
(02	R/S	P37	
ED	R/S	₽Ч₽	
104	R/S	Y5=258 (0 (3,5 ( )	
	R/S	x5=57 (5520.123	
	R/S	PNR 57	
PNR or 0	R/S		

After the calculation the intersection will be stored, if the pointnumber differs from zero.

## 2.5.2 Perpendicular on a Line

The program determines the base point  ${\bf S}$  of a point  ${\bf P3}$  on a straight line defined by the points  ${\bf P1-P2.}$ 





Input in User	Mode	Display	
EEX or	XEQ SGP	LOTFUSSPUNKT	<b>←</b>
		P (7	
101	R/S	P27	
(02	R/S	P37	
E 🛛 )	R/S	Y5=258 (0   1.500	
104	R/S	x5=57 (55 (2. 195	
	R/S	PNR 57	
PNR or 0	R/S		

After the calculation the base point will be stored, if the pointnumber differs from zero.

#### 2.5.3 Intersections of a Circle and a Line

The program determines the intersections  $S_1$  and  $S_2$  of a straight line given by the points P1-P2 and a circle with radius R und Center M.





Input in User	Mode	Display	
EEX or	XEQ SGP	SEHNITT G/K	←
		P (7	
10 1	R/S	P27	
102	R/S	PM7	
ED	R/S	RAJIUS7	
75,005	R/S	Y 1=258 (97 (.749	
	R/S	x (= 57   10 5 7.8 14	
PNR or 0	R/S	PNR 17	
	R/S	Y2=258 (064.837	
	R/S	X2=57 (094 (454	
	R/S	PNR 27	
PNR or 0	R/S		

If there is no solution, then the message **"KEIN 5EHNITT"** will be shown.

If there is only one solution,  ${\bf S}_1$  and  ${\bf S}_2$  have the same coordinates. After the calculation the two intersections will be stored, if the pointnumbers differ from zero.

#### 2.5.4 Intersections of two Circles

The program calculates the intersections  $S_1$  und  $S_2$  of two circles defined by the centers  $M_1$  und  $M_2$  and the radius  $R_1$  und  $R_2.$ 





Input in User	Mode	Display	
EEX or	XEQ SGP	SEHNITT K/K	
		M (7	<b>~</b>
101	R/S	M27	
(02	R/S	RAJIUS (7	
40.000	R/S	RAJIUS 27	
50,005	R/S	Y 1=258 (004.720	
	R/S	X (= 57 (0960.280	
PNR or 0	R/S	PNR 17	
	R/S	YZ=2580960280	
	R/S	x2=5711004.765	
	R/S	PNR 27	
PNR or 0	R/S		

If there is no solution, then the message <code>"KEIN 5EHNITT"</code> will be shown.

If there is only one solution,  ${\bf S}_1$  and  ${\bf S}_2$  have the same coordinates. After the calculation the two intersections will be stored, if the pointnumbers differ from zero.

## 2.6 Transformations

All transformation programs work with 2 points given in two coordinate systems. Every method transforms coordinates from a source system to a destination system.

#### 2.6.1 Orthogonal point calculation

With this method ordinates  $\mathbf{o}$  und abszissas  $\mathbf{a}$  in a net of aligning bases are transformed to coordinates  $\mathbf{x}, \mathbf{y}$  of a superior coordinate system. Start- and endpoint  $\mathbf{A}(\mathbf{x}, \mathbf{y})$  and  $\mathbf{E}(\mathbf{x}, \mathbf{y})$  of the base line, ordinates  $\mathbf{o}_i$  and abszissas  $\mathbf{a}_i$  are given.





Input in User	Mode	Display	]
8 or	XEQ KOKLEIN	KLEINPUNKTE	
		<b>PR7</b>	
121	R/S	PE7	1
(02	R/S	50L7	
14.16	R/S	z <u>= 50.000000</u>	
	R/S	0=0.998663	1
	R/S	0=0.706 (62	
	R/S	A=0.706 (62	
	R/S	F5=00(9	
6,25	R/S	DRJINATE7	←
ሣ.ይ 2	R/S	AJSZISSE7	
	R/S	Y = 2580960.280	
	R/S	x = 57 ( (004.765	
	R/S	PNR7	]
PNR or 0	R/S		

After input of  $P_{\mathtt{A}},~P_{\mathtt{E}}$  and the measured distance Sae the following information is displayed:

- < : direction angle  ${\tt T}_{\tt AE}$
- q : scale factor  $\textbf{S}_{\texttt{calculated}}/\textbf{S}_{\texttt{measured}}$
- : Y<sub>E</sub>-Y<sub>A</sub>/S<sub>calculated</sub>
- **a** : X<sub>E</sub>-X<sub>A</sub>/S<sub>calculated</sub>
- **FS** : S<sub>calculated</sub>-S<sub>measured</sub>

xi,yi : coordinates of points given by abszissa and ordinate

Abszissas and ordinates are entered as measured distance, the projection distortion is considered. This divides the projection distortion from the scale factor, and so the real scale factor between measured distances and calculated distances are shown!

Therefore use the programs **SYSGK**, **SYSUTM** or **SYSLOK** as explained in 2.2.

After the calculation the calculated point will be stored, if the pointnumbers differ from zero.

#### 2.6.2 Calculation of Abszissa and Ordinate

This is the inversion of the orthogonal point calculation. Here the points **A** and **E** in the superior system are given with **x**, **y** and their abszissas **a** and ordinates **o**. Abszissas **a**<sub>i</sub> and Ordinates **o**<sub>i</sub> of further given points **P**<sub>i</sub>(**x**<sub>i</sub>, **y**<sub>i</sub>) are calculated. This can be used, if points should be controlled which were given by abszissa and ordinate on a line in old fieldbooks.



Input in User	Mode	Display	
9 or	XEQ KOELEM	ORTELEMENTE	
		A35ZI55E (7	
(0.00	R/S	ORDINATE (7	
3.0 O	R/S	A35ZI55E 27	
24.16	R/S	ORDINATE 27	
3.0 Ø	R/S	ም (?	
121	R/S	P27	
(02	R/S	z <u> </u>	
	R/S	0= 100 (263	
Б,2 5	R/S	0 = 0.708000	
ዛ.Ნ	R/S	R = 7.080000	
	R/S	F5=-00(8	
	R/S	PI7	->
Э	R/S	0=3 L240	
	R/S	A=-11.15	
	R/S		_

After input of abszissas **a**, ordinates **o** and the coordinates **x**,**y** of point **A** and **E** the following information is displayed:

- < : direction angle  $T_{AE}$
- q : scale factor  $S_{\text{calculated}}/S_{\text{measured}}$
- : Y<sub>E</sub>-Y<sub>A</sub>/S<sub>calculated</sub>
- a : X<sub>E</sub>-X<sub>A</sub>/S<sub>calculated</sub>
- **FS** : S<sub>calculated</sub>-S<sub>measured</sub>
- $\mathbf{o_i}$  : ordinates of given points i
- $\mathbf{a_i}$  : abszissas of given points i

Abszissas and ordinates are shown as measured distance, the projection distortion is considered. This divides the projection distortion from the scale factor, and so the real scale factor between measured distances and calculated distances are shown!

Therefore use the programs SYSCK, SYSUTM or SYSLOK as explained in 2.2.

### 2.6.3 Helmert Transformation

The helmert transformation transforms points from a start system  $\mathbf{\hat{x}}, \mathbf{\hat{y}}\mathbf{Y}$  to a target system  $\mathbf{X}, \mathbf{Y}$ . The program works with 2 identical points  $\mathbf{P}_1$  and  $\mathbf{P}_2$  given in both systems and a number of points  $\mathbf{P}_i(\mathbf{\hat{x}}_i, \mathbf{\hat{y}}_i)$  just given in the start system. These have to be calculated into the target system  $\mathbf{P}_i(\mathbf{X}_i, \mathbf{Y}_i)$ .



\$Y



Input in User Mode		Display	
EEX or	XEQ KOKLEIN	HELMERTTRAFO	
		PI ZIEL7	
(Ø)	R/S	P2 ZIEL7	
(02	R/S	PI START?	
63	R/S	P2 START?	
55	R/S	L = 5533A3338	
	R/S	0= 1000002	
	R/S	0 = 1.0000000	
	R/S	R= (0000000	
	R/S	F5=-0.003	+
	R/S	Y START?	
9032,256	R/S	X START?	
8000.20	R/S	YZ=(000023	
	R/S	×Z=(000.008	1
	R/S	PNR7	-
PNR or 0	R/S		1

After input of the two identical points in both systems the following information is displayed:

- < : direction angle  ${\tt T}_{\tt AE}$
- $\mathbf{q}$  : scale factor  $\mathbf{S}_{\texttt{calculated}}/\mathbf{S}_{\texttt{measured}}$
- : YE-YA/Scalculated
- **a** : X<sub>E</sub>-X<sub>A</sub>/S<sub>calculated</sub>
- **FS** :  $S_{calculated} S_{measured}$

 $\mathbf{X}_i, \mathbf{Y}_i$  : coordinates of points calculated from the start system  $\mathbf{$X_i, $Y_i$}$ 

After the transformation of each point the transformed point will be stored, if the pointnumbers differ from zero.

Note: If the transformed points are saved with the same pointnumbers, the coordinates of the startsystem of these points are lost. So the points must get new pointnumbers, if the old coordinates are still needed.

## 2.7 Polar Methods

VERMPACK supports polar measurements. The 3 programs Resection, Stakeout and surveying new points are closely related.

## 2.7.1 Direction Angle and Distance

The program calculates from the coordinates of two known points PA and PE the natural distance  $S_{ae}\,$  and the direction angle of  $T_{ae}.$ 



Input in User	Mode	Display	
CHS or	XEQ RIWI	RIWI/STREEKE	
		P87	<b>~</b>
101	R/S	PE7	
102	R/S	502=14.141	
	R/S	Tar = 50.0000	

Be sure to use the wright coordinate system, to regard the wright projection!

Iherefore use the programs	SYSGK	,	SYSUTM	or	SYSLOK	as	explained	in	2.2.
----------------------------	-------	---	--------	----	--------	----	-----------	----	------

#### 2.7.2 Resection - Calculate the Station



This program determines the coordinates of a Resection FS with polar measurements to two known points P1 and P2 (Distances S, horizontal distances H and vertical Angles V).



Be sure to use the wright coordinate system, to regard the wright projection!

Therefore use the programs **SYSGK**, **SYSUTM** or **SYSLOK** as explained in 2.2.

Input in User	Mode	Display
STO or	XEQ FRSTAT	FR.STATION.
		P LINK57
101	R/S	P RECHIS7
(02	R/S	Z LINK57
333852	R/S	5 LINK57
E 5.2 )	R/S	Z RECHIS7
(00.2365	R/S	S RECHIS7
(2.98	R/S	R LINK57
1022564	R/S	R RECHIS7
275.5689	R/S	5LR= 14.142
	R/S	F5=0023
	R/S	M= 10000256
	R/S	M= (7
R/S or 0	R/S	Y5= (0 (2633
	R/S	×5= (008.509
PNR or 0	R/S	

After entering the measurements the following values are displayed as information:

- ${\rm SLR}$  : Distance between  ${\rm P}_{\rm LEFT}$  und  ${\rm P}_{\rm RIGHT}$
- FS : Difference between SLR and the distance calculated from coordinates
- M : Scale factor, should be 1. Enter R/S on the question "M: [7" to change the scale to 1.000, or 0 to use the calculated scale.

#### 2.7.3 Resection - Stakeout Points

This program is directly related to the resection program. Staking out known points **ABST.PKT** from the resection **FS** is possible.

The program calculates the target direction  $\protect\ensuremath{\$R}$  and the target distance  $\protect\ensuremath{\$S}$  to the point to be staked out.

After setting the direction it is possible to iterate to the correct position by further measurements. For this purpose the improvements of the distance VS from the current prism location to the target are displayed after every new measurement.



Be sure to use the wright coordinate system, to regard the wright projection!

Therefore use the programs SYSGK, SYSUTM or SYSLOK as explained in 2.2.

Input in User	Mode	Display	
SST or	XEQ FRABST	POLANSTECK.	
		A 35 T.PK T 7	
E 🛛 )	R/S	\$5 = 2 5.086	
	R/S	57 = 35 7.59 <del>2</del> 8	
3 3 3 3 2 8	R/S	Z 5EM7	
25.369	R/S	5 GEM7	
(00.2365	R/S	V5=-0.28 (	

After entering the point to be staked out, the calculated distance \$S and the calculated direction \$R are displayed. The direction \$R has to be set in the total station. The distance \$S must be marked by the prism as good as possible.

Then the first measurement to the prism must be done. Vertical angle  $\mathbf{Z}_{gem}$  and distance  $\mathbf{S}_{gem}$  must be entered and the program calculates the improvement  $\mathbf{VS}$  for the distance to the target. For negative  $\mathbf{VS}$ , move the prism forward, for positive  $\mathbf{VS}$  move it backward.

If VS is small enough according to the task, the target is reached.

#### 2.7.4 Resection - Measure new Points

This program is directly related to the resection program. Measuring new points  ${\bf PI}$  from the resection  ${\bf FS}$  with the polar method is possible.



Be sure to use the wright coordinate system, to regard the wright projection!

Therefore use the programs **SYSGK**, **SYSUTM** or **SYSLOK** as explained in 2.2.

Input in User	Mode	Display	
RCL or	XEQ FRMESS	POL.AUFMASS	
		R/I72	←
3 <i>2, 12</i> 45	R/S	2717 <b>5</b>	
(00.2598	R/S	2717 <u>5</u>	
(9.2 B	R/S	542. EQ: 17	
	R/S	XI=(0(2960	
	R/S	PNR7	
PNR or 0	R/S		



R/S

### 2.8 Areacalculation

#### 2.8.1 Area of a Polygon

The program calculates the area  ${\bf F}$  of a polygon with given vertices. By the way the distances  ${\bf s}$  between the actual and the last entered point are shown.



Use the programs SYSGK, SYSUTM or SYSLOK as explained in 2.2. This divides the projection distortion from the scale factor. The displayed distances and the area are shown in natural dimensions. To close the area, use the first pointnumber also as the last pointnumber. Then the calculated area is shown after displaying the last distance. Arcs are not possible.

Input in User	Mode	Display	
R/S or	XEQ AREA	KALK.AREA	
		ም (ም	
101	R/S	P2I17	
(02	R/S	5= 14.141	
	R/S		_
bei PNR=P1	R/S	F= (004849	

#### 2.8.2 Heron's Formula



This program calculates the area of a triangle given by the three sides  ${\tt a},\,{\tt b}$  and  ${\tt c}.$ 



Input in User	Mode	Display	
or	XEQ HERON	FLRHERON	
		SEITE 07	
5.8 (	R/S	SEITE 67	
ч.73	R/S	SEITE c7	
9.9 (	R/S	F = 9. (95	_

If the sides of the triangle must be calculated from coordinates, to calculate the natural distances, use the program "Direction Angle and Distance". Remember to use the correct coordinate system!

## 3 Appendix

## 3.1 Listings

These are the original listings. Angel Martin has partially modified and improved the code in the module in order to increase the speed. HEPAX-Functions are listed as "XROM 7,xx''.

Punktverwaltung			
LBL "VERWALT"	LBL "DELPKT"	LBL "GETP"	XROM 07,27
LBL "SETPKT"	"PKT LOESCHEN"	SF 25	FC? 25
"PKT EINGABE"	AVIEW	FIX 00	GTO 07
AVIEW	PSE	STO 00	CF 25
PSE	LBL 03	CLA	SF 28
LBL 00	SF 25	ARCL 49	"OK"
CF 29	FIX 00	0	PROMPT
FIX 00	"PNR?"	XROM 07,36	FIX 03
"PNR?"	PROMPT	FC? 25	GTO "RENPKT"
PROMPT	STO 00	GTO 06	LBL 07
STO 00	CLA	CF 25	SF 28
"RECHTS?"	ARCL 00	RCL 48	"GESCHEITERT"
PROMPT	XROM 07,23	1000	PROMPT
STO 01	CF 25	/	FIX 03
"HOCH?"	FIX 03	0.002	GTO "RENPKT"
PROMPT	GTO 03	+	LBL 08
STO 02	LBL "SETP"	RCL 48	1
XEQ "SETP"	RCL 00	+	ST+ 41
GTO UU	X=0?	XROM 07,18	RCL 42
LBL "GETPKT"	RTN	FIX 03	10
"PKT ABFRAGE"	SE 25	CLX	/
AVIEW	CLA ETV 00	RIN IDI OC	STO 42
IDI 01	ADCI 00	LDL UO	T
LDL VI	ARCL 00	PUNKI FERLI	- V<02
SF 25	J	PROMPT	
FIX 00	XROM 07,07	RICHIIGE NR?	KIN NEC 00
"PNR?"	FC? 25	PROMPT	XEQ 08
PROMP'I'	XEQ IO	STO 49	R'I'N
STO 00	SF 25	GTO "GETP"	LBL "LSTPKT"
CLA	FIX 03	LBL "RENPKT"	"PKT LISTE"
ARCL 00	001.002	"PNR AENDERN"	AVIEW
0	XROM 07,32	AVIEW	PSE
XROM 07,36	CF 25	PSE	FIX O
FC? 25	CLX	"ALTE NR"	XROM 7,10
GTO 05	RTN	PROMPT	XROM 7,12
CF 25	LBL 10	STO 43	6
001.002	"ERSETZEN1/0?"	"NEUE NR"	/
XROM 07,18	PROMPT	PROMPT	"FREI: "
FIX 03	STO X	STO 42	ARCL X
"Y="	X>0?	0	PROMPT
ARCI, 01	GTO 04	STO 41	FIX 3
PROMPT	"NELLE PNR?"	XEO 08	END
"X="	PROMPT	BCI. 42	
	STO 00	PCI 13	
		101 45	
	GIU DEIF	сто 42	
GIO UI	LDL V4	51U 43	
CU 191	CLA	FIX IND 41	
"PUNKT FEHLT"	ARCL 00	CF 28	
PROMPT	XROM 07,05	CLA	
FIX 03	RTN	ARCL 43	
GTO 01		SF 25	

Streckenreduktio	n
------------------	---

LBL "REDUKT"	PSE					
LBL "SPRJNAT"	CLX					
"KARTE>NATUR"	GTO "SYSUTM"					
AVIEW	LBL "SYSLOK"					
PSE	"SET LOKALSYS"					
LBL 02	AVIEW					
"S KARTE?"	PSE					
PROMPT	SF 01					
RCL IND 44	CF 02					
/	CF 03					
"SN="						
ARCL X	STO 45					
CTO 02						
T.BL. "SNATDR.T"	RCAC I UNVI					
"NATUR>KARTE"	AVIEW					
AVIEW	PSE.					
PSE	CLX					
LBL 03	GTO "SYSLOK"					
"S NATUR?"	LBL "REDUK"					
PROMPT	"ABST.MER <km>?"</km>					
RCL IND 44	PROMPT					
*	X^2					
"SK="	2					
ARCL X	/					
PROMPT	"RADIUS <km>?"</km>					
GTO 03	PROMPT					
LBL "SYSGK"	STO 00					
"SFT GK-SYS"	¥^2					
AVIEN						
AVIEW						
PSE	1					
XEQ "REDUK"	+					
CF 01	"H ELL <m>?"</m>					
SF 02	PROMPT					
CF 03	1000					
47	/					
STO 44	RCL 00					
"SYS: GK"	/					
AVIEW	CHS					
PSE	1					
CLX	+					
GTO "SYSGK"	*					
	STO 17					
SET OTM-SIS	RIN					
AVIEW	END					
PSE						
XEQ "REDUK"						
RCL 47						
0.9996						
*						
STO 46						
CF 01						
CF 02						
SF 0.3						
46						
STO 44						
STO 44						
"SYS: UTM"						
AVIEW						

101 10001		Dot 16	22.01/22
LBL "SGG"	LBL "SGK"	RCL 16	PROMP'I'
"SCHNITT G/G"	"SCHNITT G/K"	RCL 15	FIX UU
AVIEW	AVIEW	DOI OF	"PNRI ?"
PSE VEO UCOULU	FSE	RCL 05	PROMPT
XEQ "GSU1"		+ CTTO 15	STO 00
RCI 10		PCT 14	A-0: CTO 02
BCL 04	STO 49	BCL 04	XEO "SETP"
-	4	-	LBL 02
RCL 33	STO 48	RCL 15	RCL 11
*	XEO "GETP"	RCL 05	RCL 16
RCL 11	"P2?"	-	+
RCL 05	PROMPT	R-P	RCL 17
-	STO 49	Х<>Х	Х<>Ү
RCL 32	7	STO 17	P-R
*	STO 48	RCL 10	RCL 05
-	XEQ "GETP"	RCL 14	+
RCL 30	"PM?"	-	STO 02
RCL 33	PROMPT	RCL 11	X<>Y
*	STO 49	RCL 15	RCL 04
RCL 31	10	-	+
RCL 32	STO 48	R-P	STO 01
^	XEQ "GETP"	STO 16	FIX U3
_	RADIUS:	RCL 14	12-
/	PROMPT	RCL 04	ARCL X
STO 34	RCL IND 44	-	PROMPT
XEQ "GSU3"	*	RCL 15	"X2="
END	STO 13	RCL 05	ARCL 02
LBL "SGP"	RCL 07	-	PROMPT
"LOTFUSSPUNKT"	RCL 04	R-P	FIX 00
AVIEW	-	STO 11	"PNR2?"
PSE	STO 14	RCL 13	PROMPT
XEQ "GSU1"	RCL 08	X^2	STO 00
"P3?"	RCL 05	RCL 16	X=0?
PROMPT	-	X^2	GTO "SGK"
STO 49	STO 15	X>Y?	XEQ "SETP"
16	RCL 10	GTO 01	GTO "SGK"
STO 48	RCL 04	-	LBL 01
XEQ "GETP"	-	SQRT	"KEIN SCHNITT"
RCL 16	RCL 14	STO 16	PROMPT
RCL 04	*	RCL 11	GTO 03
_	RCI, 11	X<>Y	END
BCT. 30	RCT. 05	-	
*	_	PCI 17	
PCT 17	PCT 15	V <nv< td=""><td></td></nv<>	
	* *		
RCL 05		P-K	
-	+	RCL US	
RCL 31	RCL 14	+	
*	X^2	STO 02	
+	RCL 15	Х<>Ү	
RCL 30	X^2	RCL 04	
X^2	+	+	
RCL 31	/	STO 01	
X^2	STO 16	FIX 03	
+	RCL 14	"Y1="	
/	*	ARCL 01	
STO 34	RCL 04	PROMPT	
XEQ "GSU3"	+	"X1="	

## Schnittberechnungen

END	STO 14	ARCL 02
Unterprogramme	Schnittberechnunger	n 1-3
01 LBL "GSU1"	23 LBL "GSU2"	45 LBL "GSU3"
02 "P1?"	24 "P3?"	46 RCL 31
03 PROMPT	25 PROMPT	47 RCL 34
04 STO 49	26 STO 49	48 *
05 4	27 10	49 RCL 05
06 STO 48	28 STO 48	50 + 51 amo 00
07 XEQ "GETP"	29 XEQ "GETP"	51 STO UZ
00 PZ:	30 "P4?" 31 DDOMDT	52 RCL 30
10 STO 49	32 STO 49	53 KCL 54
11 7	33 13	55 RCT. 04
12 STO 48	34 STO 48	56 +
13 XEO "GETP"	35 XEO "GETP"	57 STO 01
14 RCL 07	36 RCL 13	58 0
15 RCL 04	37 RCL 10	59 STO 03
16 -	38 -	60 FIX 03
17 STO 30	39 STO 32	61 "YS="
18 RCL 08	40 RCL 14	62 ARCL 01
19 RCL 05	41 RCL 11	63 PROMPT
20 -	42 -	64 "XS="
21 STO 31	43 STO 33	65 ARCL 02
22 RTN	44 RTN	66 PROMPT
		67 FIX 00
		68 "PNR S?"
		69 PROMPT
		70 STO 00
		71 X=0?
		72 RTN
		73 XEQ "SETP"
		74 FIX 03
		75 RTN
		76 END

LBL "KREISM"	-	X=0?
"KREISMITTELPKT"	RCL 14	GTO "KREISM"
AVIEW	COS	FIX 00
PSE	*	STO 00
LBL 02	+	XEQ "SETP"
"P1?"	RCL 15	FIX 03
PROMPT	/	GTO "KREISM"
510 49	CH5	LBL VI
ч STO 48	BCL 13	DROMPT
XEO "GETP"	COS	GTO 02
"P2?"	*	END
PROMPT	RCL 07	
STO 49	RCL 04	
7	+	
STO 48	2	
XEQ "GETP"	/	
"P3?"	+	
PROMPT STO 49	DCL 13	
10	SIN	
STO 48	RCL 16	
XEQ "GETP"	*	
RCL 07	CHS	
RCL 04	RCL 08	
-	RCL 05	
RCL 08	+	
RCL 05	2	
-	/	
R-P	+	
Х<>Ү	STO 02	
STO 13	0	
BCL 10	STO 03	
BCL 04	BCL 02	
_	RCL 05	
RCI. 11	-	
DCI 05	v^2	
RCL 05	A Z	
- D_D	RCL 01	
K-P	KCL 04	
	-	
STO 14	X^Z	
RCL 13	+	
-	SQR'I'	
CHS	STO 17	
SIN	RCL IND 44	
2	/	
*	FIX 03	
X=0?	"R="	
GTO 01	ARCL 17	
STO 15	PROMPT	
RCL 10	"ҮМ="	
RCL 07	ARCL 01	
-	PROMPT	
RCL 14	"XM="	
SIN	ARCL 02	
*	PROMPT	
RCL 11	"PNR M?"	
RCL 08	PROMPT	

## Kreismittelpunkt aus drei Randpunkten

#### Schnitt Kreis-Kreis

LBL "SKK"	RCL 10	RCL 14
"SCHNITT K/K"	RCL 12	*
AVIEW	/	-
PSE	STO 15	RCL 04
LBL 03	RCL 11	+
"M1?"	RCL 12	STO 01
PROMPT	/	"Y2="
STO 49	STO 16	ARCL X
4	RCL 14	PROMPT
STO 48	*	"X2="
XEQ "GETP"	CHS	ARCL 02
"M2?"	RCL 13	PROMPT
PROMPT	RCL 15	FIX 00
STO 49	*	"PNR2?"
7	+	PROMPT
STO 48	RCL 05	STO 00
TAN	+	X=0?
TAN	STO 02	GTO 02
XEQ "GETP"	RCL 14	XEQ "SETP"
"RADIUS 1?"	RCL 15	LBL 02
PROMPT	*	FIX 03
RCL IND 44	RCL 16	GTO 03
*	RCL 13	END
STO 06	*	
"RADIUS 2?"	+	
PROMPT	RCL 04	
PCI IND 11	+	
*	с <u>то</u> 01	
	510 01	
STO 09	FIX 03	
RCL 08	"Y1="	
RCL 05	ARCL 01	
-	PROMPT	
STO 10	"X1="	
BCL 07	ARCI 02	
PCT 04		
ICEL 04		
-	FIX UU	
STO 11	"PNR1?"	
R-P	PROMPT	
STO 12	STO 00	
X^2	X=0?	
RCL 06	GTO 01	
X^2	XEQ "SETP"	
+	т.вт. 01	
PCT 09	ETX 03	
X2	KCL 14	
-	RCL 16	
RCL 12	*	
2	RCL 15	
*	RCL 13	
/	*	
STO 13	+	
V^2	DCI 05	
A 2	KCL UJ	
CHS	+	
RCL 06	STO 02	
X^2	RCL 16	
+	RCL 13	
SQRT	*	
STO 14	BCL 15	

## Orthogonalberechnungen

TOT UPONETNU	UV7_U	I DI UNOVI ETNU	SHO 02
	ADCI 02	"KIFINDINKTE"	S10 02
AVIEW	PROMPT	AVIEW	ARCI. 02
PSE	FIX 00	PSE	PROMPT
"P1 ZIEL?"	"DNR 2"	"PA2"	FTX 00
PROMPT	PROMPT	PROMPT	"PNR?"
STO 49	STO 00	STO 49	PROMPT
10	x=02	10	STO 00
STO 48	GTO 01	STO 48	X=0?
XEO "GETP"	END	XEO "GETP"	GTO 01
"P2 ZIEL?"		"PE?"	XEO "SETP"
PROMPT		PROMPT	GTO 01
STO 49		STO 49	END
13		13	
STO 48		STO 48	
XEO "GETP"		XEO "GETP"	
"P1 START?"		0	
PROMPT		STO 04	
STO 49		STO 05	
4		STO 07	
STO 48		"Sae?"	
XEQ "GETP"		PROMPT	
"P2 START?"		RCL IND 44	
PROMPT		*	
STO 49		STO 08	
7		XEO "KO"	
STO 48		LBL 01	
YEO "CETE"		"OPDINATE?"	
AEQ GEIF		ORDINATE:	
XEQ "KO"		PROMPT	
LBL 01		RCL IND 44	
"Y START?"		*	
PROMPT		RCL 04	
RCL 04		-	
-		"ABSZISSE?"	
"X START?"		PROMPT	
PROMPT		BCL IND 44	
PCI 05		*	
KCL 05		DOI OF	
-		RCL 03	
R-P		-	
RCL 17		R-P	
*		RCL 17	
Х<>Х		*	
RCL 18		Х<>Х	
+		RCL 18	
Х<>Ү		+	
P-R		X<>Y	
X<>Y		P-R	
DOI 10			
RCL IU		X<>1	
+		KCL IU	
STO 01		+	
FIX 03		STO 01	
"YZ="		FIX 03	
ARCL X		"Y="	
PROMPT		ARCL X	
X<>Y		PROMPT	
RCI. 11		X<>V	
		DOI 11	
+		KCL II	
STO 02		+	

## Orthogonalberechnungen

LBL "KOELEM"	X<>Y	LBL "KO"
"ORT.ELEMENTE"	RCL 11	RCL 07
AVIEW	+	RCL 04
PSE	STO 02	-
"ABSZISSE 1?"	"A="	RCL 08
PROMPT	ARCL 02	RCL 05
STO 10	PROMPT	-
"ORDINATE 1?"	GTO 01	R-P
PROMPT		STO 16
STO 11		STO 17
"ABSZISSE 2?"		Х<>Ү
PROMPT		STO 18
STO 13		RCL 13
"ORDINATE 2?"		RCL 10
PROMPT		-
STO 14		RCL 14
"P1?"		RCL 11
PROMPT		-
STO 49		R-P
4		STO 19
STO 48		RCL 17
XEO "GETP"		/
"P2?"		STO 17
PROMPT		Х<>Ү
STO 49		RCL 18
7		-
, GTTO 40		0.00.10
510 48		510 18
XEQ "GETP"		FIX 06
XEQ "KO"		"<="
LBL 01		ARCL X
"PI?"		PROMPT
PROMPT		"Q="
STO 49		ARCL 17
21		PROMPT
510 48		RCL 18
XEQ "GETP"		SIN
RCL 21		RCL 17
RCL 04		*
-		")="
RCL 22		ARCL X
RCL 05		PROMPT
_		PCT 18
ת ת		
K-P		
RCL 17		RCL 17
*		*
X<>Y		"A="
RCL 18		ARCL X
+		PROMPT
X<>Y		RCI, 19
B-B		PCT 16
		тот то
X<>Y		
RCL 10		CHS
+		FIX 03
STO 01		"FS="
FIX 03		ARCL X
"O="		PROMPT
ARCI. X		RTN
FROMPT		END

LBL "FREIEST"	R-P	STO 00	-
LBL "FRSTAT"	STO 10	X#0?	FIX 03
"FR.STATION"	XEO 00	XEO "SETP"	"VS="
AVIEW	CHS	GTO 04	ARCL X
PSE	RCL 22	LBL "FRABST"	PROMPT
"P LINKS?"	+	"POL.ABSTECK"	CLX
PROMPT	XEQ 01	AVIEW	GTO 02
STO 49	STO 11	PSE	LBL 00
4	RCL 10	RCL 21	CLX
STO 48	RCL 15	RCL 11	Х<>Ү
XEQ "GETP"	FIX 03	-	LBL 03
"P RECHTS?"	"SLR="	STO 17	X<=Y?
PROMPT	ARCL X	FIX 00	GTO 01
STO 49	PROMPT	"ABST.PKT?"	RTN
7	-	PROMPT	LBL 01
STO 48	"FS="	STO 49	400
XEQ "GETP"	ARCL X	33	+
RCL 07	PROMPT	STO 48	RTN
RCL 04	RCL 15	XEQ "GETP"	LBL "FRMESS"
-	RCL 10	RCL 33	"POL.AUFMASS"
RCL 08	/	RCL 31	AVIEW
RCL 05	FIX 07	-	PSE
-	"M="	RCL 34	RCL 21
R-P	ARCL X	RCL 32	RCL 11
STO 15	PROMPT	-	-
XEO 00	FIX 05	R-P	STO 17
STO 22	STO 10	RCT. 10	"R <t>?"</t>
ETV 04	UM-1 2	/	
FIX 04		/	PROMPT
"Z LINKS?"	PROMP'I'	STO 19	RCL 17
PROMPT	1	RCL IND 44	-
SIN	X=Y?	/	XEQ 03
"S LINKS?"	STO 10	FIX 03	"Z <i>?"</i>
PROMPT	RCL 16	"\$S="	PROMPT
RCL IND 44	*	ARCL X	SIN
*	RCT. 11	PROMPT	"9<1>2"
*	V CNV	VEO 00	
	X<>1	ALQ UU	
STO 16	P-R	RCL 17	RCL IND 44
"Z RECHTS?"	X<>A	+	*
PROMPT	RCL 04	XEQ 03	*
SIN	Х<>Х	STO 18	P-R
"S RECHTS?"	-	FIX 04	Х<>Ү
PROMPT	STO 01	"\$R="	RCL 31
BCI. IND 44	STO 31	ARCT. X	+
*	EIV 02		сто 01
	FIA US	FROMPT	
^	"YS="	TRT 05	X T=
STO 23	ARCL 01	"Z GEM?"	ARCL X
"R LINKS?"	PROMPT	PROMPT	PROMPT
PROMPT	Х<>Ү	X#0?	Х<>Х
STO 21	RCL 05	STO 12	RCL 32
"R RECHTS?"	Х<>Ү	RCI, 12	+
PROMPT	_	STN	STO 02
DOI 01	000 00	DOI 10	
KCL ZI	STO U2	RCL 19	"X1="
-	STO 32	RCL 20	ARCL X
STO 18	"XS="	-	PROMPT
	ADOI 00	V<>V	"PNR?"
RCL 23	ARCL UZ		T 141/ •
RCL 23 P-R	PROMPT	/	PROMPT
RCL 23 P-R RCL 16	PROMPT	/ / "S GEM?"	PROMPT STO 00
RCL 23 P-R RCL 16	PROMPT "PNR S?"	/ "S GEM?"	PROMPT STO 00

## Freie Stationierung mit Absteckungs- und Aufnahmemodul

	II ODED!			
EQ	"SETP"			
BL	04			
ND				

#### Flächenberechnungen

LBL "HERON"	LBL "AREA"	FIX 03
"FLA.HERON"	"KALK.AREA"	"S="
AVIEW	AVIEW	ARCL X
PSE	PSE	PROMPT
LBL 00	0	RCL 05
"SEITE a?"	STO 07	STO 02
PROMPT	"P1?"	RCL 04
STO 00	PROMPT	STO 01
"SEITE b?"	STO 49	RTN
PROMPT	STO 10	LBL 04
STO 01	1	FIX 02
+	STO 48	"F= "
"SEITE c?"	XEQ "GETP"	RCL 07
PROMPT	LBL 01	ABS
STO 02	"P <i>?"</i>	ARCL X
+	PROMPT	PROMPT
2	STO 49	GTO "AREA"
/	RCL 10	END
STO 03	-	
RCL 00	x=0?	
-	SF 04	
RCL 03	RCL 49	
RCL 01	4	
-	STO 48	
*	XEO "GETP"	
RCI. 03	×	
RCL UZ	XEQ US	
-	FS?C 04	
*	XEQ 04	
RCL 03	GTO 01	
*	LBL 02	
SORT	RCL 05	
FTX 02	RCL 02	
	ICH 02	
<u>F</u> =	-	
ARCL X	RCL 04	
PROMPT	RCL 01	
RCL 00	+	
RCL 01	*	
+	2	
PCT 02		
RCL 02		
+	RCL IND 44	
FIX 03	X^2	
"U="	1	
ARCL X	ST+ 07	
PROMPT	RTN	
GTO 00	LBL 03	
CIO UU		
UND		
	RCL U2	
	-	
	X^2	
	RCL 04	
	RCL 01	
	_	
	¥^2	
	AZ	
	+	
	SQRT	
	RCL IND 44	
	/	

Höhe und Höhenfußpunkt im Dreieck
LBL "HHFP"
"DREIECK"
AVIEW
PSE
LBL 00
"SEITE a?"
PROMPT
X^2
"SEITE b?"
PROMPT
STO 00
x^2
-
"SEITE c?"
PROMPT
STO 01
x^2
+
RCL 01
2
1
FIX 03
"P="
ARCL X
PROMPT
RCL 01
-
CHS
"Q="
ARCL X
PROMPT
V^)
CHS
RCL 00
X^2
+
SQRT
"H="
ARCL X
PROMPT
CTO 00
END

#### LBL "ABKBS" END LBL "ABKBT" "ABST.SEHNE" "ABST.TANG." AVIEW AVIEW PSE PSE "RADIUS?" "RADIUS?" PROMPT PROMPT STO 00 STO 00 "L SEHNE?" LBL 01 PROMPT "X?" 2 PROMPT / STO 01 STO 01 "dx?" RCL 00 PROMPT / STO 02 ASIN X=0? COS SF 04 CHS LBL 02 1 FIX 03 + RCL 01 "A=" RCL 00 \* ARCL X STO 02 PROMPT LBL 01 RCL 00 "X?" X^2 RCL 01 PROMPT STO 03 X^2 "dX?" -PROMPT X<0? STO 04 GTO 03 X=0? SQRT SF 04 CHS LBL 02 RCL 00 FIX 03 + "0=" RCL 03 "A=" ARCL X ARCL X PROMPT PROMPT FS?C 04 CHS GTO 01 RCL 01 RCL 02 + ST+ 01 X^2 GTO 02 CHS LBL 03 RCL 00 "ZU WEIT" X^2 PROMPT + GTO 01 SORT END RCL 02 + RCL 00 "0=" ARCL X PROMPT FS?C 04 GTO 01 RCL 04 ST+ 03

Bogenabsteckung von der Tangente und der Sehne

GTO 02